

# **DISCRIMINATING CLEAR SKY FROM CLOUD WITH MODIS**

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## Outline of Presentation

- \* Definition of MODIS Cloud Mask
- \* Features of Cloud Detection
- \* Heritage of Cloud Algorithms
- \* Components of the MODIS Cloud Algorithm
  - IR Threshold
    - histogram
    - temporal continuity
    - moisture correction
    - scene uniformity
  - Reflectance
    - examples from MAS
  - Non surface viewing spectral bands
    - 1.38  $\mu\text{m}$  near IR cirrus detection
    - 13.9  $\mu\text{m}$  discrimination of high cloud
    - 6.7  $\mu\text{m}$  help in the polar regions
  - Vis/IR Multispectral Approaches
- \* Inputs and Outputs
- \* Summary

## Definition of MODIS Cloud Mask

- \* will indicate whether FOV has an unobstructed view of the earth surface
- \* will try to indicate whether clear FOV is affected by cloud shadows
- \* will be generated at the three resolutions of the MODIS data  
(250 meter, 500 meter, and 1000 meter)
- \* input is assumed to be calibrated and navigated level 1B data
- \* cloud mask will be determined for good data only  
(ie. FOVs where ch 1, 2, 6, 8, 19, 22, 26, 27, 29,  
31, 32, and 35 have radiometric integrity)
- \* incomplete or bad data will create holes in the cloud mask.

## General Features of Cloud Detection

- \* generally characterized by higher reflectance and lower temperature than the underlying earth surface
- \* simple visible and infrared window threshold approaches offer considerable skill in cloud detection
- \* there are many surface conditions when this characterization of clouds is inappropriate, most notably over snow and ice
- \* some cloud types such as cirrus, low stratus, and small cumulus are difficult to detect because their radiances do not contrast sufficiently with that from the surface below.
- \* cloud edges cause further difficulty since the MODIS FOV is not completely cloud nor clear
- \* spatial coherence tests offer confirmation scene uniformity
- \* multispectral approaches mitigate many single band deficiencies

MODIS Cloud Mask will benefit from previous work

- \* ISCCP (International Satellite Cloud Climatology Project)  
Rossow (1989, 1993), Rossow et al. (1989) and Seze and Rossow (1991)  
VIS/IRW band thresholds from leo and geo clear-sky composite
- \* CLAVR (Cloud AVHRR algorithm)  
Stowe et al.(1994)  
five VIS/IR bands for 2 x 2 GAC data in spectral and spatial tests
- \* CO<sub>2</sub> Slicing  
Wylie et al. (1994)  
CO<sub>2</sub> bands characterize thin cirrus
- \* Spatial Coherence  
Coakley and Bretherton (1982)  
standard deviation versus mean radiance produces arches

MODIS Cloud Mask will have considerable advantage

- \* it has multispectral information and high spatial resolution
- \* 12 VIS and IR bands will be used to mitigate difficulties  
at 5 km x 5 km scale

## Components of MODIS Cloud Algorithm

### Reflectance Uniformity Test

max and min values close indicate cloud free scene uniformity  
 $r_{.66}$  over land and  $r_{.87}$  over ocean

daytime only, must be ecosystem specific  
must account for satellite zenith and view angle

### Reflectance Ratio Test

$r_{.87}/r_{.66}$  is between 0.9 and 1.1 for cloudy regions  
if true then further tests should be performed to test for cloud

must be ecosystem specific

### Reflectance Threshold Test

$r_{3.9} > 6\%$  considered to be cloudy and  $< 3\%$  considered to be snow/ice

problems in bright deserts

### Infrared Window Brightness Temperature Threshold and Difference Tests

$$BT_{11} < 270$$

$$BT_{11} + a_{PW} * (BT_{11} - BT_{12}) < SST$$

$$BT_{11} + b_{PW} * (BT_{11} - BT_{8.6}) < SST$$

where  $a_{PW}$  and  $b_{PW}$  are determined from a lookup table as a function of total precipitable water vapor (PW).

$BT_{3.9} - BT_{11} > 3$  indicates presence of partial of thin cloud cover

$BT_{11} - BT_{6.7}$  show large negative difference for clear sky over the Antarctic Plateau winter

IR threshold and difference tests sensitive to surface emissivity and atmospheric PW, dust, and aerosols

### Infrared Window One-Dimensional Histogram Tests

$$BT_{thres} = BT_{max} - \sigma$$

need surface uniformity

### Near IR Thin Cirrus Test

$r_{1.38} > \text{threshold}$  indicates presence of thin cirrus cloud

ambiguity of high thin versus low thick cloud (resolved with  $BT_{13.9}$ )  
problems in high terrain

### CO<sub>2</sub> Channel Test for High Clouds

$$BT_{13.9} < \text{threshold}$$

possible problems in high terrain

### Infrared Window Radiance Spatial Uniformity

### Infrared Window plus Visible Threshold Tests

### Two-Dimensional Infrared and Visible Histogram Analysis

best over oceans, must be characterized by ecosystem

### Detection of Cloud Shadows

difficult

### Automated Classification Methods

tied to quality flag, uses texture tests

## Inputs

- \* sun angle, azimuthal angle, and viewing angle
- \* land/water map at 1 km resolution  
(MODIS will develop a better one subsequently)
- \* topography at 10 minute resolution  
(Navy character map will provide this;  
as well as rugged versus plateau terrain)
- \* ecosystems at 10 minute resolution  
(map of 59 classes of ecosystems available)
- \* snow/ice from yesterday known at 1 km resolution  
(ancillary sea versus land discrimination at 18 km res)
- \* surface temperatures (sea and land) at 1 degree resolution  
(NMC analysis or yesterdays MODIS observations)



# Channels used in generation of MODIS Cloud Mask

Channel Number	Wavelength (microns)	Used in Cloud Mask (B indicates backup to another channel)
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## Reflected radiation

1	0.659	Y
2	0.865	Y
3	0.470	N
4	0.555	B
5	1.240	N
6	1.640	Y
7	2.130	N
8	0.415	Y
9	0.443	N
10	0.490	N
11	0.531	N
12	0.565	N
13	0.653	N
14	0.681	N
15	0.750	N
16	0.865	N
17	0.905	N
18	0.936	N
19	0.940	Y?
26	1.375	Y
20, 21	3.750	B
22	3.959	Y
23	4.050	N
24	4.465	N
25	4.515	B

## Emitted radiation

20, 21	3.750	B
22	3.959	Y
23	4.050	N
24	4.465	N
25	4.515	B
27	6.715	Y
28	7.325	N?
29	8.550	Y
30	9.730	N
31	11.030	Y
32	12.020	Y
33	13.335	N
34	13.635	N
35	13.935	Y
36	14.235	N

## Outputs (24 bit word for each FOV)

bit	content
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summary of all algorithms

1	obstructed fov (yes/no)
2	quality flag

ancillary information

1	snow/ice
2	land/water
1	sunglint found (yes/no)

results from classes of cloud algorithms

1	IR threshold found cloud
1	IR temperature differences found cloud
1	vis threshold found cloud
1	vis ratio found cloud
1	near IR thin cirrus test found cloud
1	CO2 high cloud test found cloud
1	IR spatial tests found cloud
1	vis spatial tests found cloud
1	multiple layers identified
1	cloud shadow found
1	1.6 found cloud

room for additional information

6	spare
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## Summary

- \* MODIS Cloud Mask indicates if FOV has unobstructed view of earth surface
- \* Collaboration with members of CERES Science Team
- \* Heritage algorithms incorporated  
(ISSCP, CLAVR, CO2, the golden arches)
- \* Initially conservative approach will be adopted  
(if any test is positive, mask will indicate obstructed FOV)
- \* Multispectral approaches will alleviate single band deficiencies
- \* Prelaunch testing with HIRS/AVHRR and MAS data
- \* Ecosystem specific algorithms will be developed

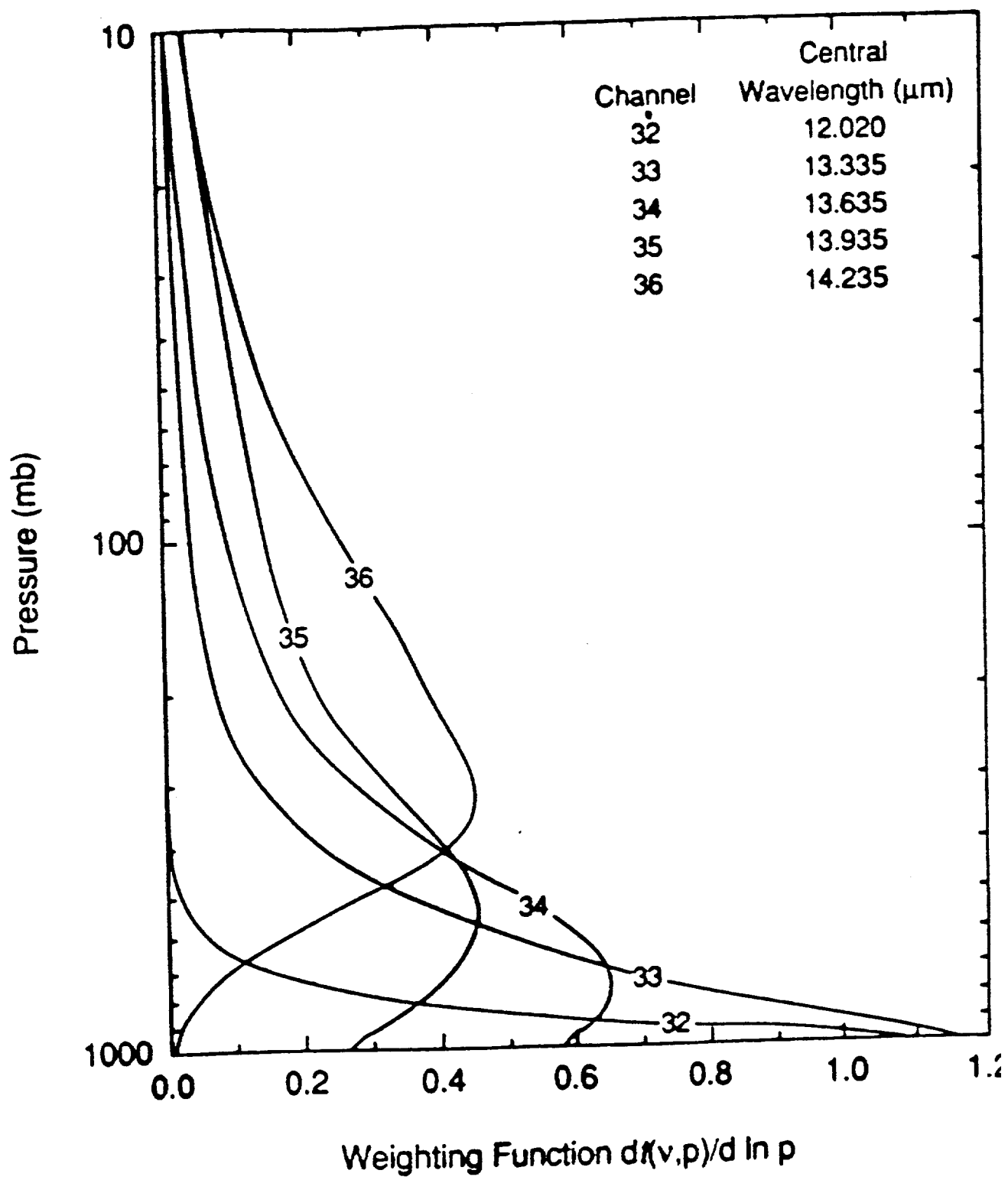


Figure 1

## STANDARD ATMOSPHERE

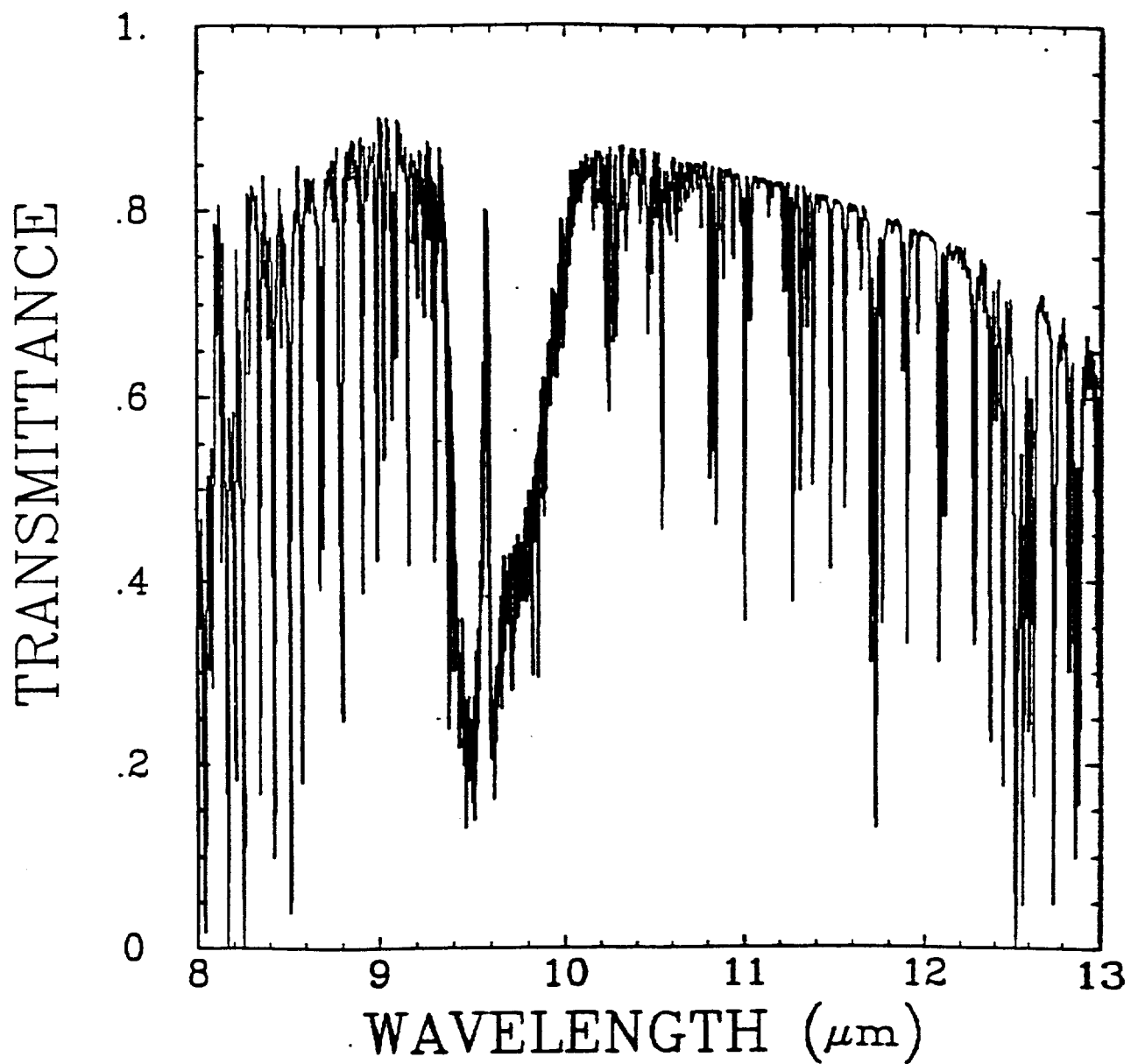
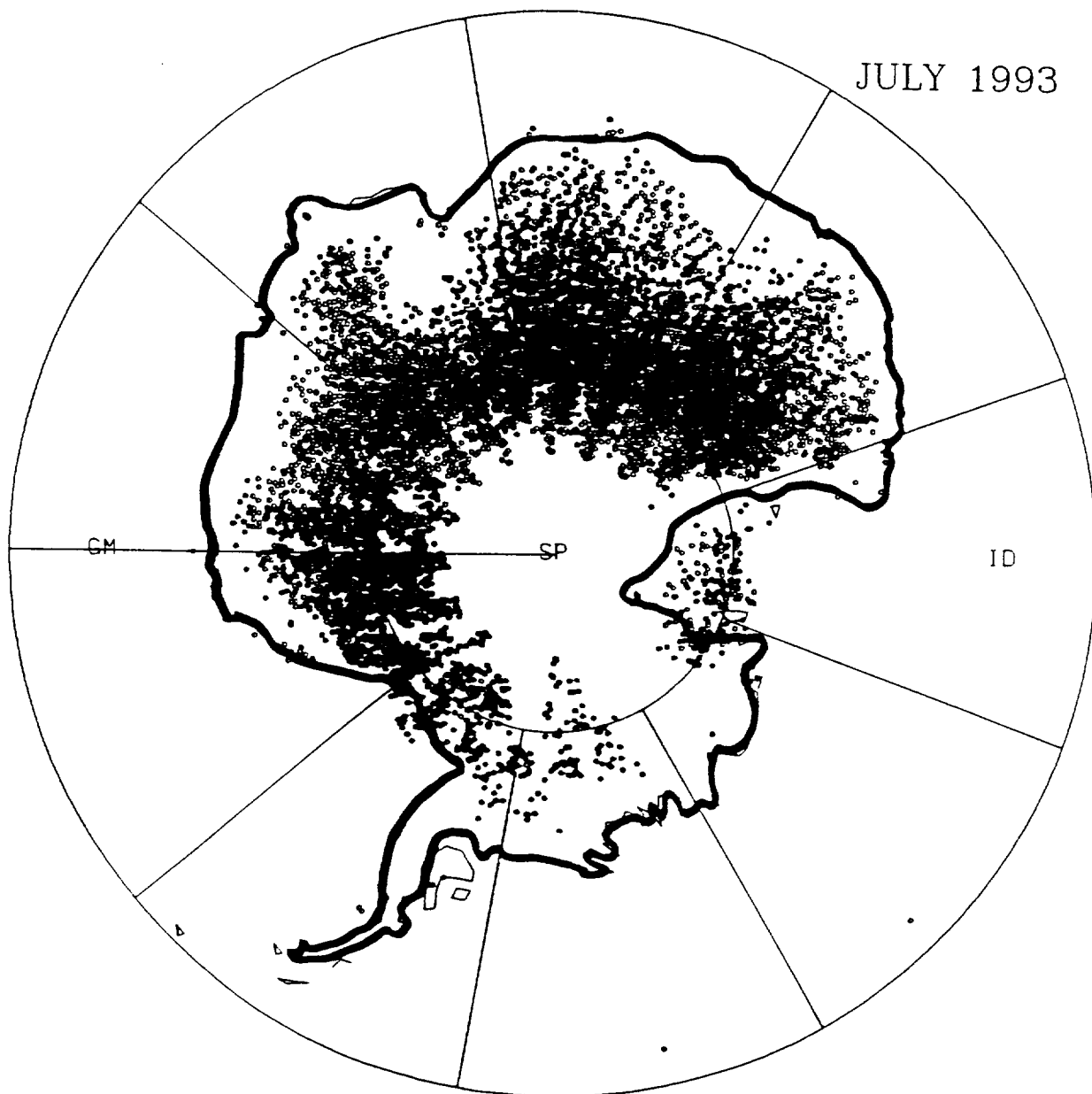


Figure 2. HIS (High resolution Interferometer Sounder) total transmittance spectra for a standard atmosphere across the 8-13  $\mu\text{m}$  window.

JULY 1993



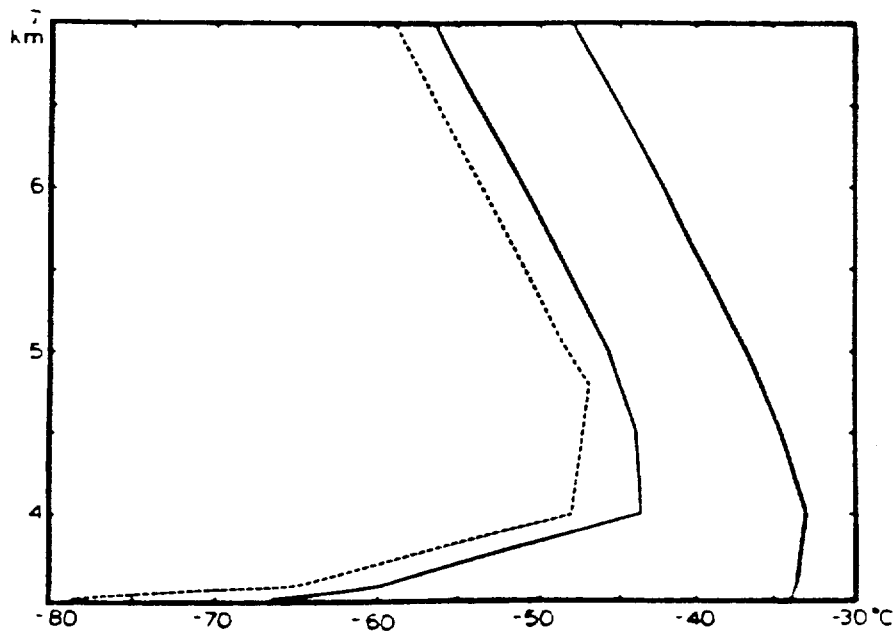
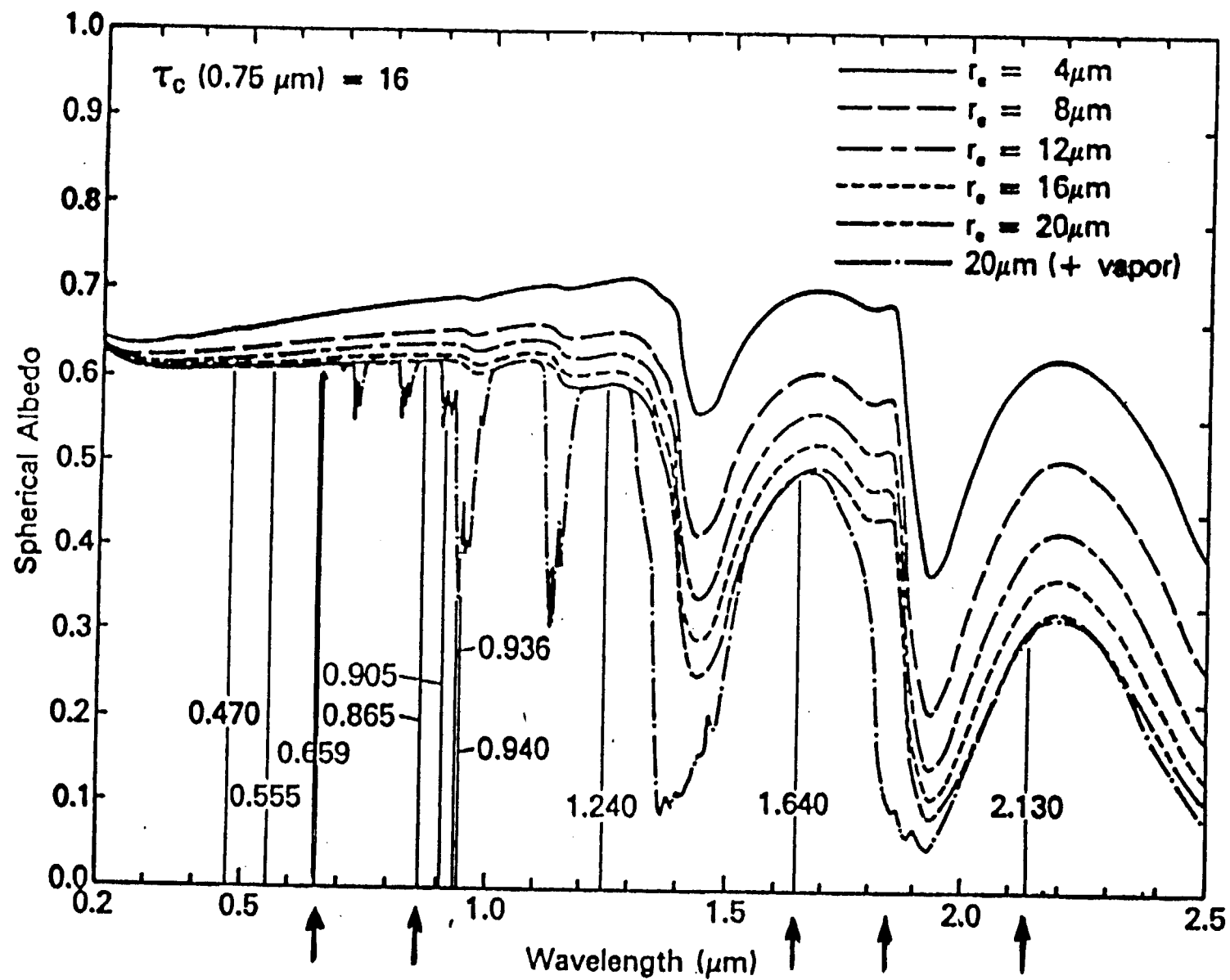
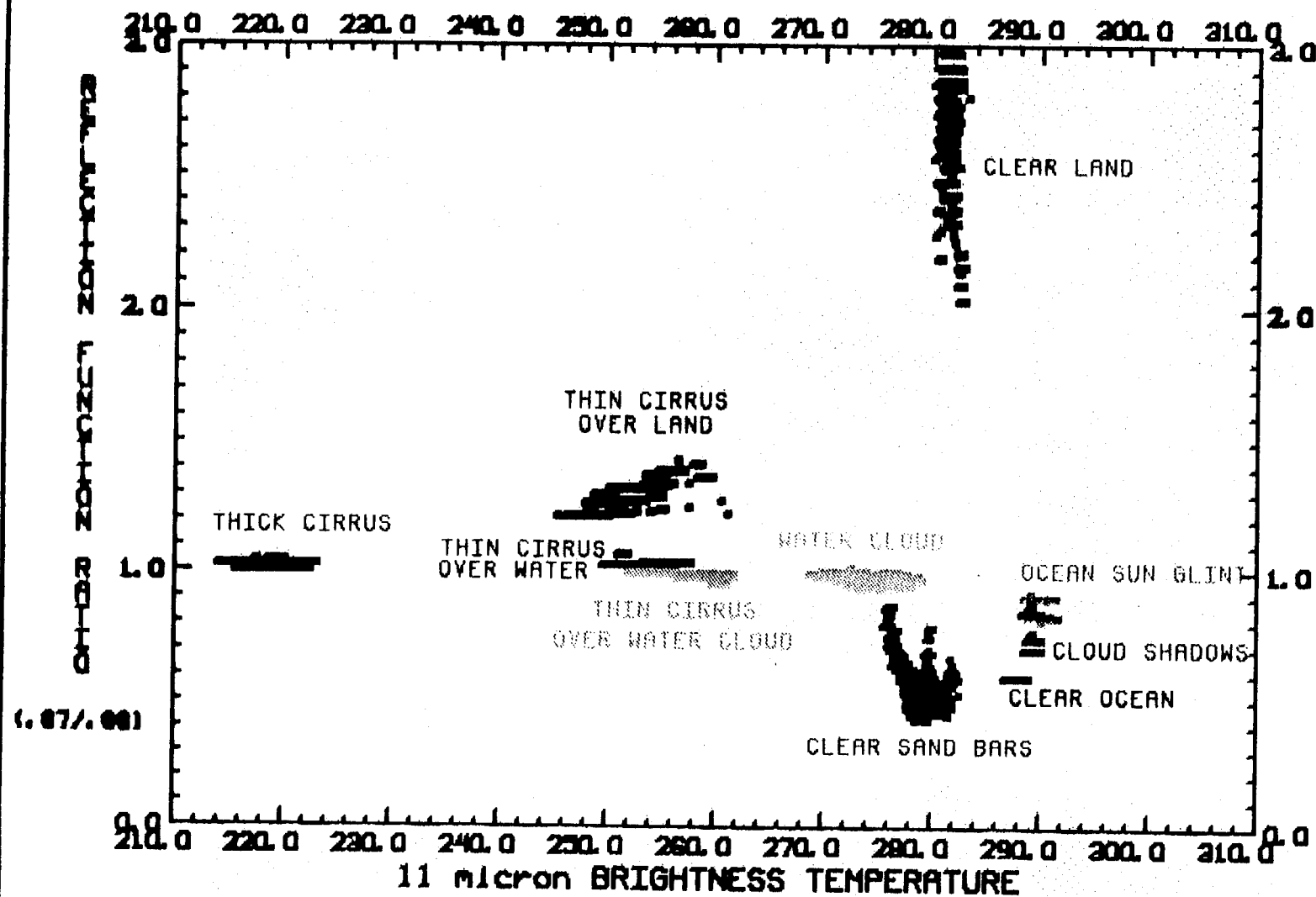


Figure 3.8: Vostok (3488 m). Average temperature between the surface and 7000 meters above sea level in ~~summer~~ summer (December and January) and winter (April-September). Also included is an example of an extremely strong inversion on June 2, 1960 (from Schwerdtfeger, [1970]).

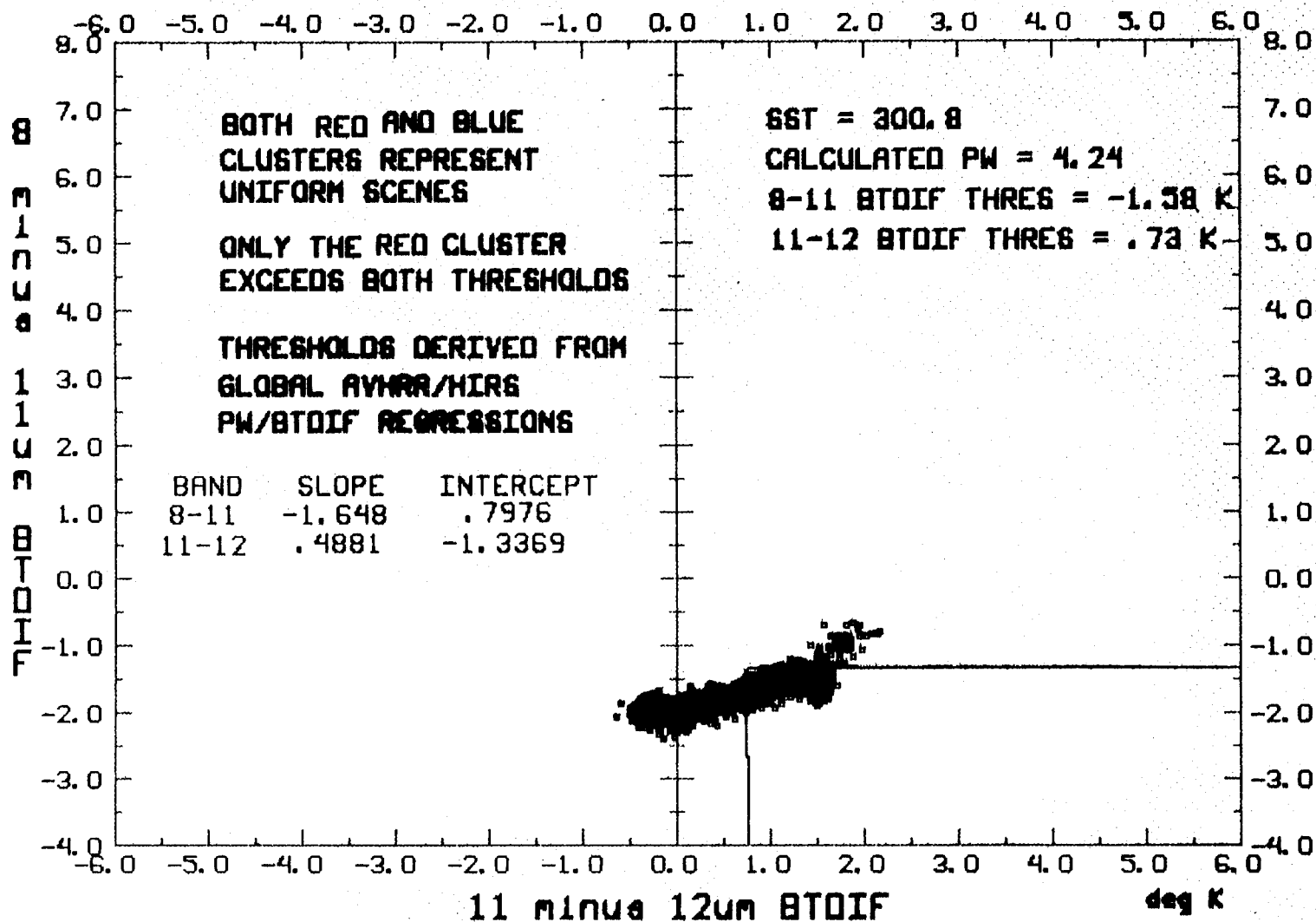




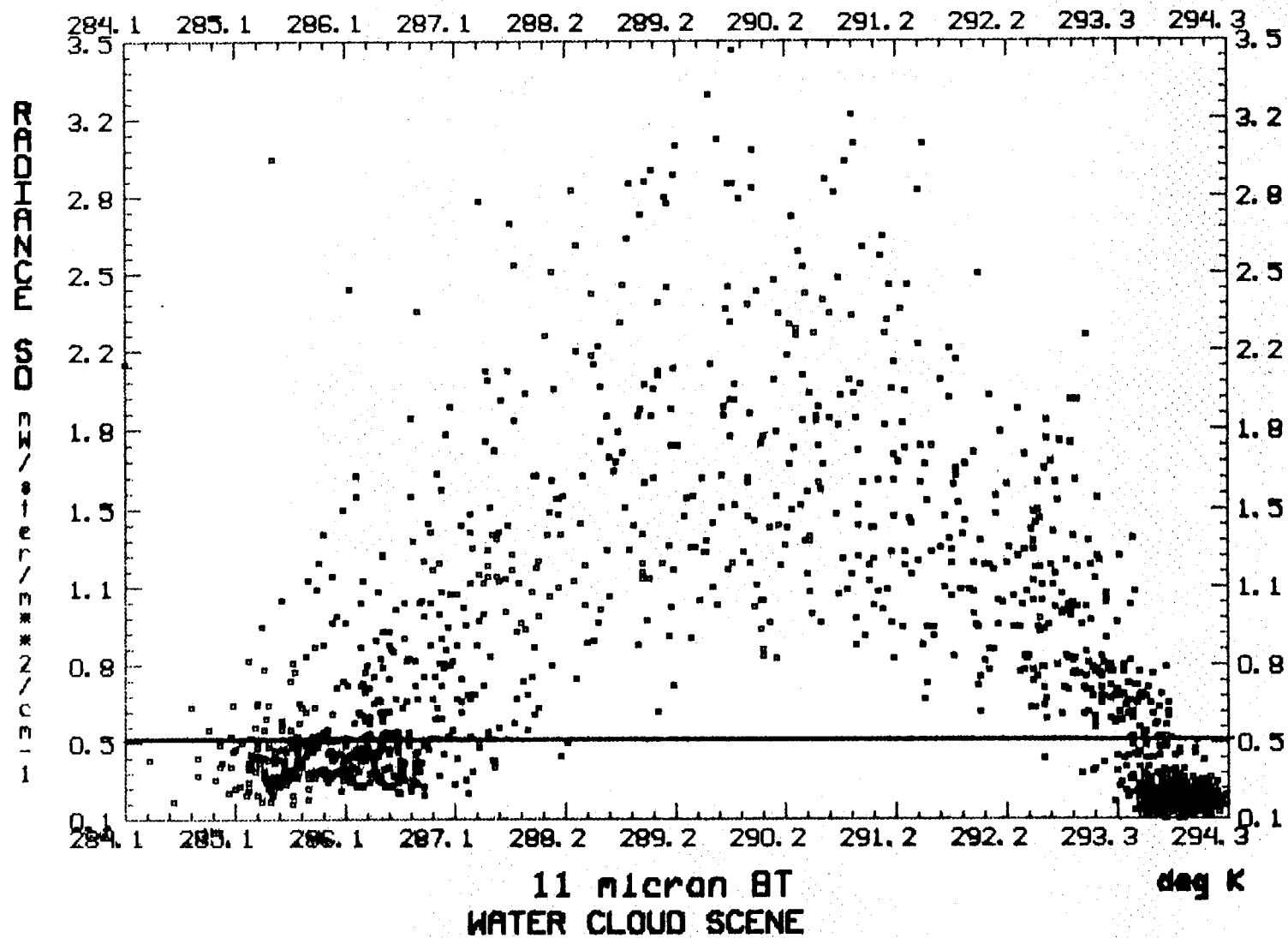
# SCENES FROM MAS TOGA/COARE DATA 26 JAN 1993



# MAS WATER CLOUD BTOIF 18 JAN 1993



# SCENE UNIFORMITY FOR 18 JAN 1993



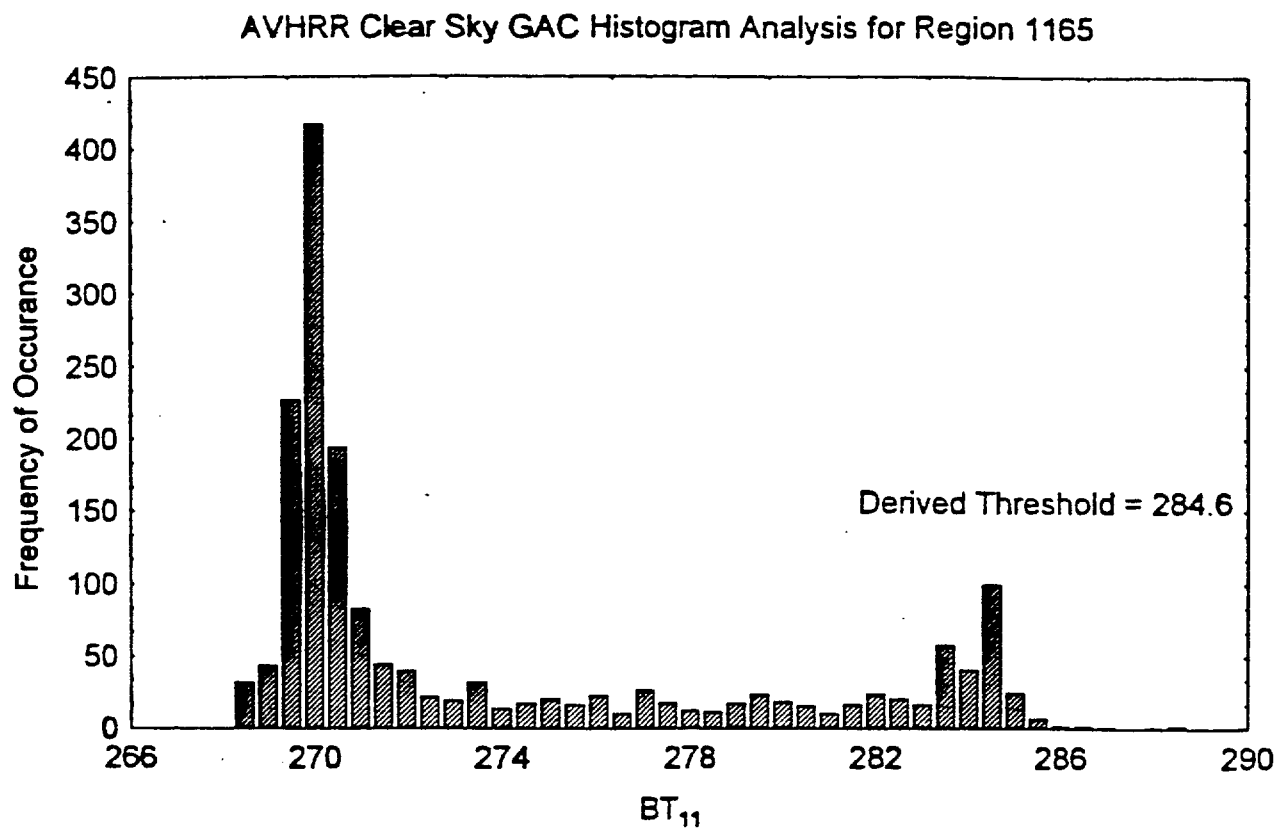


Figure 6. Example of infrared histogram analysis technique using AVHRR GAC data for a 2.5° x 2.5° ocean region. The derived clear-sky BT<sub>11</sub> threshold is 284.6 K.

TEMPORAL TEST  
Collocated AVHRR and HIRS/2 Observations  
2.5 by 2.5 degree ocean region

